

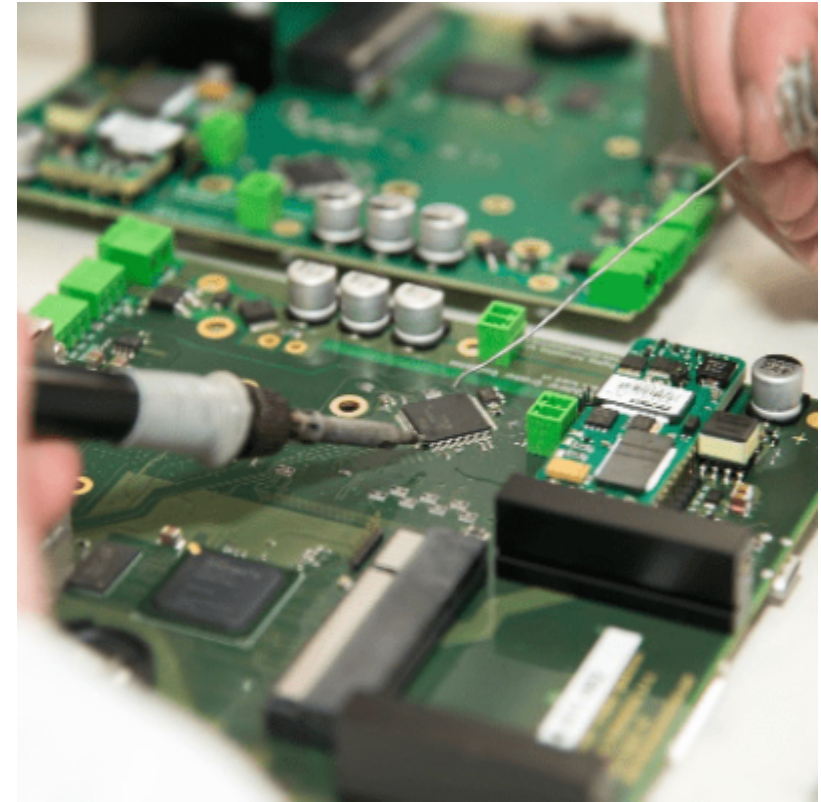
FPGA Applications for Automotive

FPGAs and SoCs are on the rise!

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Introduction

- › A typical automotive product uses the cheapest MCU (only that matters for a series of millions).
- › When higher performance is required – choose an SoC (ARM Cortex-A family).
- › The major disadvantage of MCUs/SoCs – a set of peripherals/functions is predetermined.
- › FPGAs are great for projects which requires:
 - › Flexibility to support future standards and interfaces,
 - › Scalability to implement the desired number of interfaces/peripherals,
 - › Cost-efficiency for low volume production (prototypes or test equipment).
- › We would like to present some of our FPGA-based projects.



MGB (Modular Frame Grabber)

- › Captures video/static frames w/o compression
- › Acts as a pass-through device
- › Streams video over Ethernet or HDMI
- › Supports multiple automotive video interfaces via modules with an OpenLDI interface
- › Spartan-6 implements an OpenLDI sink and frame buffer with a PCI Express link
- › Quad-core ARM SoC provides video compression, HDMI output, and network services
- › Disadvantage: only one video interface at the time, while a modern car has several displays



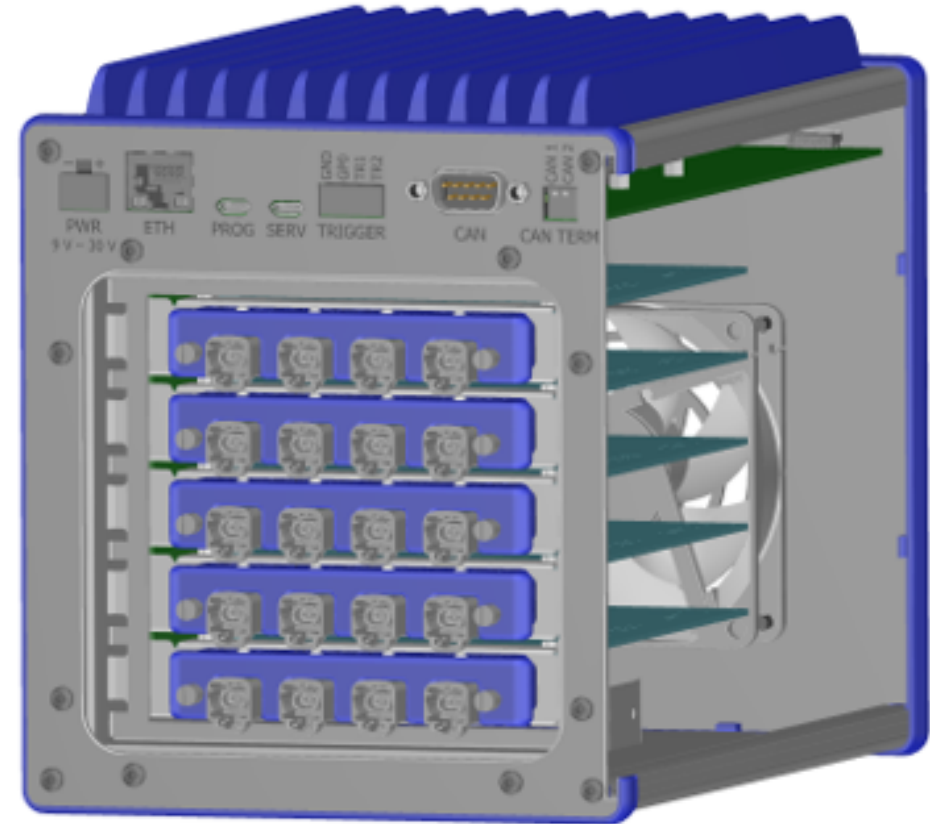
FrameGrabber 4

- › The successor of the MGB uses Artix-7
- › Also uses interchangeable interface modules
- › Increased scalability, up to 4 sink/source OpenLDI interfaces + GTX lines for future use (DisplayPort)
- › Faster and wider PCI Express interface
- › A multi-stream DisplayPort 1.2 video source implementation is currently under development



FrameGrabber 4 Box

- › The MGB on steroids!
- › Up to 5 PCIe cards mean 20 video interfaces or more
- › nVidia Jetson provides PCIe connectivity, video processing, and networking
- › Intended for users who require a standalone device like the original MGB



A car-sharing project

- › Specifications and implementation details are confidential except:
 - › Certified Automotive product
 - › „Low-volume“ project (means 1 million units by VW)
 - › Based on Xilinx Zynq
 - › FPGA implements CAN-FD & LIN interfaces
 - › Processors are running a Linux distribution to handle user requests and to provide control



CANSim4 & CANSim5

- › CAN simulator, which emulates car environment such as speed, dimming level, position, etc.
- › CANSim4 is based on NXP MCU
- › (Future) CANSim5 aims significantly higher:
 - › Ability to run a full-size OS or RTOS
 - › Networking support for remote operations
 - › Doubling or tripling the number of interfaces (CAN-FD/LIN)
 - › Flexibility to implement new standards with current hardware
 - › Scalability to target the desired price (and set of functions) by modifying a BOM only
- › Xilinx Zynq seems to be the ideal solution



Conclusion

- › The presented uses-cases show:
 - › FPGAs (usually paired with SoC) became common even in automotive domain
 - › Such projects requires engineers capable of:
 - › Designing and debugging electronics and PCBs on the lowest level
 - › Proficient with MCUs, SoCs, and FPGAs
 - › Proficient with programming baremetal/RTOS/Linux applications and/or drivers
 - › Designing a system architecture
 - › A bit of mechanical engineering
- › **Overall: our engineer is required to posses complex knowledge to deal with complex problems ...**

Alternative definition of „*complex*“ engineering problem:

You got quite imaginary specifications and you are expected to develop and deliver a real product.

On the other hand, that is the exact moment when engineers can shine with their skills and creativity 😊

Disclaimer: This joke does not represent the opinions of Digiteq Automotive s.r.o.

Thank you for your attention!

